## REPAIRABILITY INDEX CALCULATION AND PRESENTATION OF THE PARAMETERS WHICH ALLOWED TO ESTABLISH IT

Robotic vacuum

ate of calculation Please fill out			
Producer's or importer's name or trademark	DREAME		
Producer or importer adress	17th Floor, Leighton Centre, 77 Leighton Road, Causeway Bay, Hong kong		
Producer's or importer's model identifier	Please fill out		

This "FINAL\_SCORE" tab in English is purely indicative. In order to meet regulatory obligations, only the "NOTE\_FINALE" tab in French (see the next tab) is to be sent. Note: The results are automatically reported in the French tab.

Criteria	Sub-criteria	Score of subcriterion /10	Weighting factor of subcriterion	Score of criterion /20	Total criteria scores /100
CRITERION 1 : DOCUMENTATION	1.1 Availability of the technical documentation and other documentation related to user and maintenance instructions	10,0	2	20,0	76,7
DISASSEMBLY, ACCESSIBILITY, TOOLS,	2.1 Ease of disassembly parts from List 2*	4,2	1		
	2.2 Necessary tools (List 2)	10,0	0,5	14,2	
	2.3 Fasteners characteristics parts from List 1** and List 2	10,0	0,5		
CRITERION 3 : AVAILABILITY OF SPARE PARTS	3.1 Availability over time parts from List 2	0	1		
	3.2 Availability over time parts from List 1	0	0,5	2,5	
	3.3 Delivery time parts from List 2	5,0	0,3	2,5	
	3.4 Delivery time parts from List 1	5,0	0,2		
CRITERION 4 : PRICE OF SPARE PARTS	4. Ratio between price of parts from list 2 to the price of the product	10,0	2	20,0	
CRITERION 5 : SPECIFIC CRITERION	5.1 Accesibility of usage-counter to consumers	10,0	1		
	5.2 Free remote assistance	10,0	0,5	20,0	
	5.3 Possibility to reset softwares	10,0	0,5		
		Reparability index on 10			7,7

<sup>\*</sup> list 2: list of a maximum of 3 to 5 spare parts (depending on the category of equipment concerned) whose broken or malfunctioning parts are the most frequent;

<sup>\*\*</sup> list 1: list of a maximum of 10 other spare parts (depending on the category of equipment concerned) whose good condition is necessary for the operation of the equipment.